

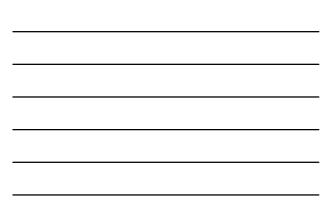
## Contents

- What is the limiting factor in 3D digitization process today?
- Do we need a definition of "Object Complexity"?
- What should be the characteristics of such a definition?
- How Complexity is defined How is it measured?
- How Complexity is connected to Quality?
- How Complexity is connected to Technology?
- How Complexity is connected to purpose of 3D digitization?
- Synthesis a Decision-making workflow

2

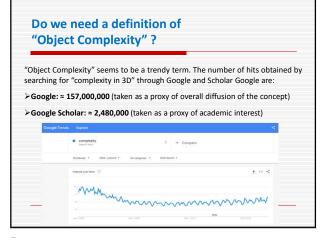
Current technology Limits					
Available technology	Max. resolution/accuracy				
Micro-scanning	1 µm				
Photogrammetry	0.5 cm				
Laser scanning point cloud	0.5 cm				
GNSS topography/surveying	1 cm				
UAV imagery	2 cm				
Satellite imagery	30 cm				

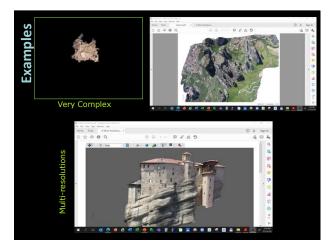
What is the limiting factor in 3D digitization



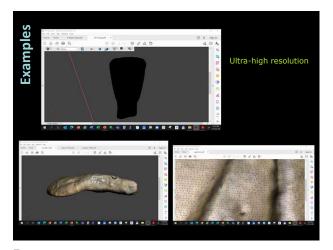
	rpose Limits
Possible purpose of use	Max. required resolution/accuracy
3D printing replica 1:1 of small objects. Digital archive at max. resolution	2 µm
3D printing replica 1:1 of large objects. Digital archive at max. resolution	1 cm
Web viewing	200μm (= 0,2 mm at viewing distance)

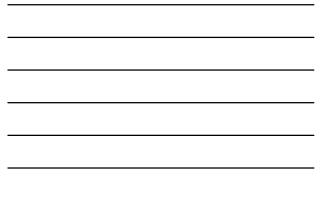












## ...and to make things worse.... Cultural Memory includes

- monuments and archaeological sites
- museum objects
- photographs
- prints (books, journals and newspapers)
- archival documents
- sound and audiovisual material
- intangible heritage

8

### Do we need a definition of "Object Complexity" ?

- > object complexity as a value of its own
- which cannot be estimated subjectively,
- it can be defined only <u>AFTER we make all the measurements</u> on the object (making it useless for 3D digitization planning and decision-making) and
- it is <u>neutral to intended use</u> (making it useless for choosing the best technology)

ARGUMENT:

We need to shift our attention from the "Object complexity" to "Model complexity".

This means that our focus is not the complexity of the real object per se (which is connected to the data capture phase), but the complexity of the produced model (which is connected to the data processing phase).

#### ... take an example

- Suppose that we have a 3m statue of a rather complicated marble surface.
- The purpose of the 3D digitization is to use it into a virtual museum of Roman History.

This means that the produced model will be seen on a computer screen at a max of 3x zoom factor and a max scale of 1:50 of the original statue.

This translates to a model with a dimension of 6cm (= $3m \times 1.50$  scale) which can be zoomed by a factor of 3x (thus the final model should be seen in full detail corresponding to a **virtual object of size 18cm** (= 6cm x 3)).

This should be able to be examined seamlessly at a normal viewing distance, which corresponds to a typical optical resolution of 0,2mm or  $200\mu$ m. Dividing the max. dimension of 18cm by this resolution we end up 9,000 surface-defining triangles of a max dimension  $200\mu$ m each.

This is the model fidelity as defined by the fit-for-purpose.

10

#### example ....

If we now go back to the original object, and let's assume that the modelling process degrades the fidelity of the original measurements by a relaxation factor of eg.  $\lambda=2$ . That is, the original measurements are smoothed and generalized through the modelling phase, and so they lose half of their original accuracy of representation. So, in order to make sure that the final model keeps its aimed characteristics, we need to make original measurements twice as accurate than the model specifications, i.e. we need **18,000 triangles** to describe the object surface.

Dividing the object dimension (3m) by the number of triangles (18,000) we end up with a resolution (or max dimension of the triangle side) 1,67cm for the 3D digitization measurements.

**Final conclusion:** no matter what the complexity of the original object is, we will not be able to see smaller details (or measurement errors) than say **1,5cm** on the object surface. This is the actual complexity that matters to us, and according to this we may plan the use of the optimum technology, and the recording strategy.

11

### **Summarizing** : Do we need a definition of "Object Complexity" ?

- Complexity will determine to high degree the technology to be used. E.g. it is quite difficult and unproductive to use Photogrammetry to record the complexity of a cave, whereas Laser scanning is the suggested technology in this case.
- Complexity is the missing connection between the Quality and the Purpose-of-use. E.g. although possible it is useless to use UAV imagery to map a large surrounding landscape of an archaeological site, whereas satellite imagery is much preferable.
- Complexity imposes restrictions on both the technology and intended use. E.g. surface transparency violates basic photogrammetric rules, preventing the use of this technology; also low reflected radiation of certain surface material poses restrictions to laser scanning.
- Complexity connects Quality, Accuracy and Completeness as long as it expresses parameters like object size or resolution requirements. E.g. complex interiors call for fusion of technologies, exploiting the merits of each one, while requirements for multiple resolutions/accuracies are often dictated by multiple uses of the same 3D acquired material.

## What should be the characteristics of such a definition?

Complexity as a property is typically defined as (Oehmen et al, 2015):

- Containing multiple parts
- Possessing a number of connections between the parts
- Exhibiting dynamic interactions between the parts; and the behavior produced as a result of those interactions cannot be explained as the simple sum of the parts

In the 3D digitization context, more relevant is the term "surface complexity" or "roughness".

**Roughness metrics** either use surface roughness index, or variability in the surface normal vectors. This is quantified by the deviations in the direction of the normal vector of a real surface from an ideal plane and is mainly used in Metrology/Mechanics.

13

## What should be the characteristics of such a definition?

What is important to note is that the size of the local neighborhood dictates the scale at which surface roughness is characterized. Thus, roughness or surface complexity is scale-variant, and is assessed at a scale that is meaningful with respect to the specific application.

Summing up, the definition of the object complexity should have the following characteristics:  $% \label{eq:complexity}%$ 

- > It refers to both 3D data capture and data processing/modelling
- It is calculated subjectively
- $\succ\,$  It is estimated **before** the data acquisition phase
- It connects to Quality, Technology, Purpose of use
- It provides a meaningful tool for planning both the data acquisition and the 3D modelling

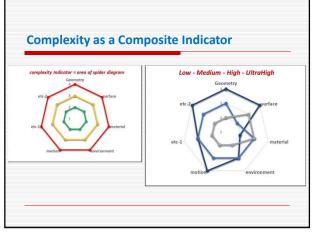
14

# How Complexity is defined – How is it measured?

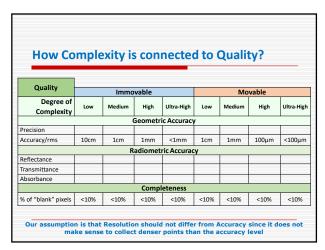
- Geometric/Structural Complexity This refers to the resolution, the degree of detail, the number of features, the number of surfaces or faces of the object. Given that triangles are the fundamental geometric unit that is used by many graphics systems, the number of triangles is a key metric for complexity. Another important aspect of Geometric complexity is its relationship to the size of the object. It is clear that the absolute number of triangles does not reflect the object complexity, and only the relative number is useful. We, thus, propose to use the ratio number of triangles per unit surface instead.
- Surface/Texture Complexity This refers to RGBA colors as well as multi-textures. RGBA accommodates simple imagery information that captures Red-Green-Blue-Alpha values in separate channels where Alpha represents opacity
- Material Complexity This refers to object complexity originated by the material and its physical characteristics (e.g. Reflectance, Transmittance, Absorbance, etc.). which can impose limits or barriers to active or passive data capture technologies.
- Environment, motion, etc.

measured?								
Complexity <sup>3</sup>		Imr	novable			Mo	vable	
Degree of Complexity	Low	Medium	High	Ultra-High	Low	Medium	High	Ultra-Hij
	Ge	ometric/St	tructural Co	mplexity / I	Resolutio	n		
Number of triangles per unit surface	<10/m	<100/m	<1,000/m	>1,000/m	<1/cm	<10/cm	<100/cm	>100/cr
Min. triangle dimension	10cm	1cm	1mm	<1mm	1cm	1mm	100µm	<100µn
		Surface/Te	exture Com	plexity / Res	olution			
RGBA texture	•	•	•	•	•	•	•	•
Multi-textured	•	•	•	•	•	•	•	
		<u></u>	Material Co	mplexity				
concrete	•	T		· · · ·	[			· · · · ·
brick	•							
metal		•	•			•	•	
ceramic/clav			•					
glass								
stone		•	-					











Technologies								
recimologies	Immovable				Movable			
Degree of Complexity	Low	Medium	High	Ultra- High	Low	Medium	High	Ultra Hig
Tac	tile							
Hand Survey								
Architecture	*				*			-
Тород	raphy				8			
GNSS	T	•	•	•	1			
Traditional topographic survey	•		•	*		1 0		
Photogra	mmet	ry	1					
Close-range		•	•	•	•	•	•	•
Terrestrial	•	•	*	*				
Airborne	•		•	•				1
UAV	•	•	•					
Laser so	annin	3	()		-	· · · · ·		
Terrestrial Laser Scanner		•	•	•	•	•	•	•
Airborne LIDAR		•				1		
Mobile System						1 8		
Satellite Ren	note Se	ensing						
Low resolution-LR (>5m)					1	1 2		
High Resolution-HR (<5m)	•			Ş		6		2
Very High Resolution-VHR (<1m)								
Specialized	Techno	ology						
Desktop scanner				-		•	•	•
Hand-held Scanner		•	*	*		•	•	•
Underwater Systems					-	-		
Subsurface Systems		•	•					



Durance								
Purpose		Immo	ovable			Mo	ovable	
Degree of Complexity	Low	Medium	High	Ultra-High	Low	Medium	High	Ultra-H
	Reconna	issance l	evel (ac	curacy/res	olution	)		
<ul> <li>Condition recording</li> <li>Initial inventory /planning</li> <li>Post disaster</li> </ul>	= λ <sub>3</sub> x 10cm	=λ <sub>3</sub> x 1cm	=λ <sub>3</sub> x 1mm	= λ <sub>3</sub> x < 1mm	= λ <sub>3</sub> x 1cm	=λ <sub>3</sub> x 1mm	= λ <sub>3</sub> x 100μm	= λ <sub>3</sub> x 100μ
	Prelim	inary lev	el (accu	racy/resol	ution)			
<ul> <li>Initial investigation</li> <li>Reference data</li> </ul>	= λ <sub>2</sub> x 10cm	= λ <sub>2</sub> x 1cm	= λ <sub>2</sub> x 1mm	= λ <sub>2</sub> x < 1mm	= λ <sub>2</sub> x 1cm	= λ <sub>2</sub> x 1mm	= λ <sub>2</sub> x 100μm	= λ <sub>2</sub> x 100μι
	Deta	iled leve	l (accura	cy/resolu	tion)			
As-found condition     Archive     Monitor/maintenance     3D print/replica	= λ <sub>1</sub> x 10cm	= λ <sub>1</sub> x 1cm	=λ <sub>1</sub> x 1mm	= λ <sub>1</sub> x <1mm	= λ <sub>1</sub> x 1cm	=λ <sub>1</sub> x 1mm	= λ <sub>1</sub> x 100μm	= λ <sub>1</sub> x 100μι

High           12 x 10 x 18 cm           451,284           300 µm           Bronze           0.05 mm           0.008 mm           1.5 mm           100%           Triangulation laser           scanner           Detailed level           666,920           Detailed level	Medium           12 x 10 x 18 cm           225,642           0.8 mm           Bronze           0.05 mm           0.08 mm           1.5 mm           100%           Triangulation laser scanner           Preliminary level           125,464	Low 12 x 10 x 18 cm 22,5642 0.4 cm Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation lass scanner Reconnaissance level 12,364
451,284 300 μm Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Detailed level 666,920	225,642 0.8 mm Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Preliminary level	22,5642 0.4 cm Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation lase scanner Reconnaissance level
300 μm Bronze 0.05 mm 1.5 mm 100% Triangulation laser scanner Detailed level 666,920	0.8 mm Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Preliminary level	0.4 cm Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation lase scanner Reconnaissance level
Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Detailed level 666,920	Bronze 0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Preliminary level	Bronze D.05 mm 0.008 mm 1.5 mm 100% Triangulation lase scanner Reconnaissance level
0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Detailed level 666,920	0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Preliminary level	0.05 mm 0.008 mm 1.5 mm 100% Triangulation lase scanner Reconnaissance level
0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Detailed level 666,920	0.05 mm 0.008 mm 1.5 mm 100% Triangulation laser scanner Preliminary level	0.05 mm 0.008 mm 1.5 mm 100% Triangulation lase scanner Reconnaissance level
0.008 mm 1.5 mm 100% Triangulation laser scanner Detailed level 666,920	0.008 mm 1.5 mm 100% Triangulation laser scanner Preliminary level	0.008 mm 1.5 mm 100% Triangulation lase scanner Reconnaissance level
1.5 mm 100% Triangulation laser scanner Detailed level 666,920	1.5 mm 100% Triangulation laser scanner Preliminary level	1.5 mm 100% Triangulation lase scanner Reconnaissance level
100% Triangulation laser scanner Detailed level 666,920	100% Triangulation laser scanner Preliminary level	100% Triangulation lase scanner Reconnaissance level
Triangulation laser scanner Detailed level 666,920	Triangulation laser scanner Preliminary level	Triangulation lase scanner Reconnaissance level
Triangulation laser scanner Detailed level 666,920	Triangulation laser scanner Preliminary level	Triangulation lase scanner Reconnaissance level
scanner Detailed level 666,920	scanner Preliminary level	scanner Reconnaissance level
666,920		
		12.364
Detailed level		
	Preliminary level	Reconnaissance level
		0 4 5444 6 2 4 7 6 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8





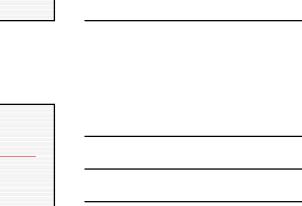
Immovable Low 32 x 10 x 22 m 491,881 10 cm

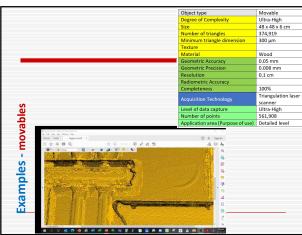
Concrete, rock, brick, wood 7 mm 4 mm 10 cm

Immovable Medium 32 x 10 x 22 m 24,594,111 1 cm

Concrete, rock, brick, wood 7 mm 4 mm 1.5 cm





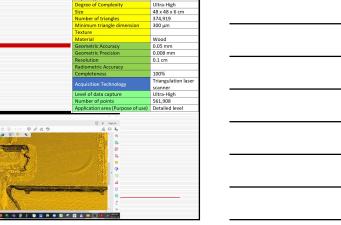


Object type Degree of Complexity

e Imber of triangles nimum triangle dimens

CL.

atorial





23

**Examples - immovables** 

